

AN13970

在 Cadence Tensilica HiFi 4 DSP 上运行 Zephyr RTOS

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应用笔记

文档信息

信息	内容
关键词	AN13970, i.MX 8M Plus, HiFi 4 DSP, Zephyr, IPC, OpenAMP, remoteproc
摘要	本文介绍了如何在 HiFi 4 DSP 上启动示例应用、HiFi 4 DSP 与主核如何通信，以及如何获取示例应用的输出。



1 介绍

业内广泛讨论如何在 Arm Cortex-A 或 Cortex-M 核上运行 Zephyr，并且已经产生了许多实例。然而，许多基于 Cortex 的 MCU 和 MPU 也选择集成片上 DSP 来分流计算密集型任务。

Cadence Tensilica HiFi 4 DSP 就是这类高性能嵌入式数字信号处理器（DSP）的示例之一，它针对音频、语音或神经网络处理进行了优化。本应用笔记重点介绍了：如何在主 Cortex-A 核上运行 Linux 操作系统的同时，在 DSP 上运行 Zephyr 实时操作系统，从而利用 DSP 的强大处理能力。

本文档包含一个简单的示例应用“hello_world”，但也可以使用其他示例。本文档将解释如下问题：

- 如何在 HiFi 4 DSP 上启动示例应用
- HiFi 4 DSP 和主核如何通信
- 如何获取示例应用的输出

在本文档中，所有示例均使用 Linux 操作系统和 Zephyr 实时操作系统的现有驱动程序和/或框架进行说明。

2 硬件平台

i.MX 8M Plus EVK 板基于 NXP i.MX 8M Plus 应用处理器，由以下部分组成：

- 四个 Arm Cortex-A53，频率高达 1.8 GHz
- 一个 Arm Cortex-M7，频率高达 800 MHz
- Cadence Tensilica HiFi 4 DSP，频率高达 800 MHz

[图 1](#) 显示了 i.MX 8M Plus EVK 板的俯视图。

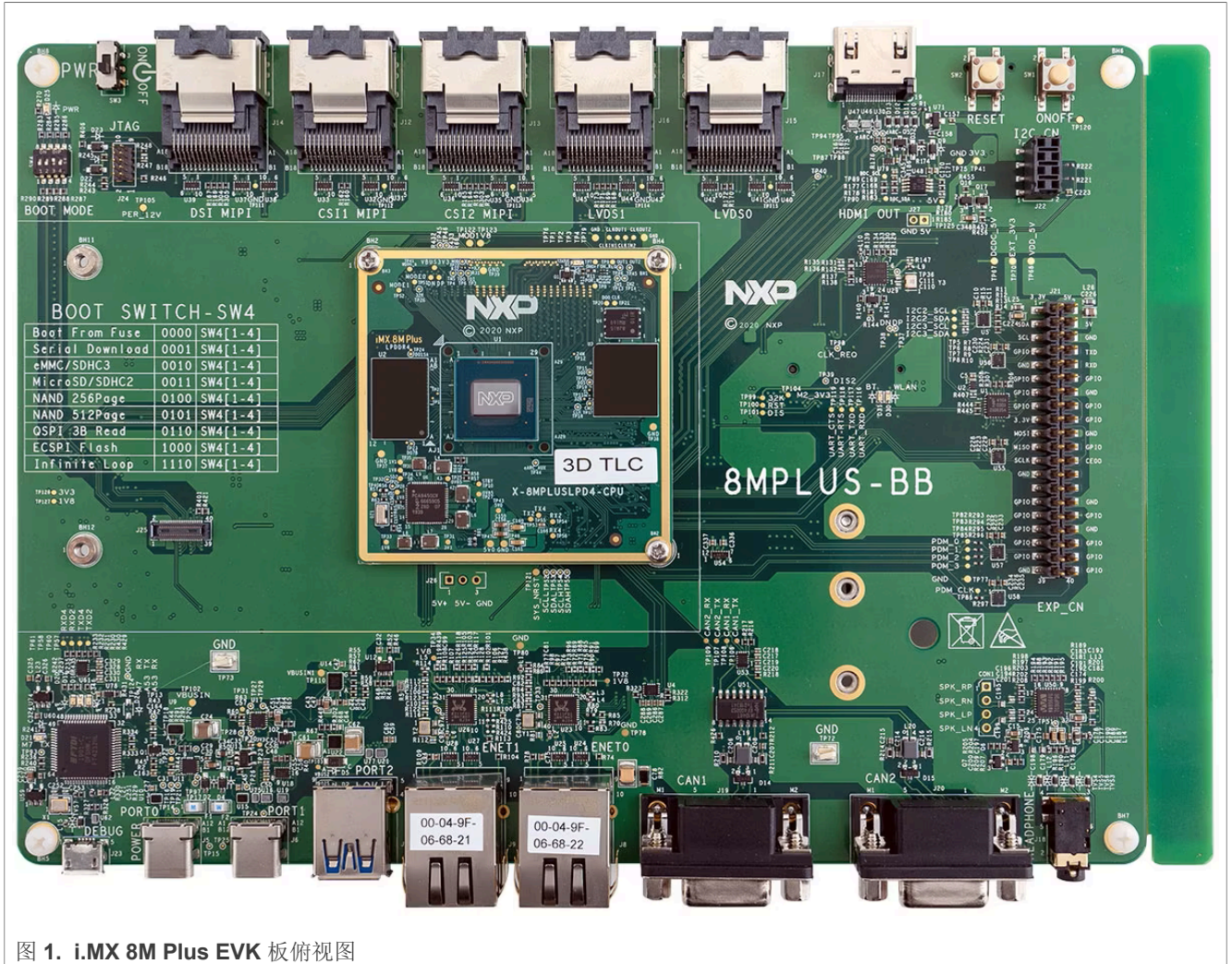


图 1. i.MX 8M Plus EVK 板俯视图

如需了解详情，请参阅 [i.MX 8M Plus EVK](#) 上的电路板信息。

3 Zephyr 操作系统

[Zephyr Project](#) 是一个可扩展的实时操作系统 (RTOS)，支持多种硬件架构，针对资源受限的器件进行了优化，并在构建时考虑了安全性。它基于小内核，专为在资源受限的系统上使用而设计。

NXP 提供 Zephyr 操作系统支持的各种评估和原型平台。开发人员能够使用包含硬件、开发工具以及传感器和器件驱动程序的真实开源项目，轻松定制符合自身需求的解决方案。Zephyr 操作系统的安全增强功能使设备管理、连接栈和文件系统的实施变得简单。

有关 Zephyr RTOS 的更多信息，请访问 www.zephyrproject.org/。

4 HiFi 四音频数字信号处理器 DSP

HiFi 四音频引擎是一款高度优化的音频处理器，可实现音频和语音编解码器以及前处理和后处理模块的高效执行。

在 Zephyr 中，支持 i.MX 8M Plus 音频 DSP 的板是 nxp_adsp_imx8m。

4.1 支持的功能

Zephyr nxp_adsp_imx8m 板的配置支持 [表 1](#) 中的硬件功能。

表 1. 支持的硬件功能

接口	控制器	驱动程序/组件
SYSTICK	On-chip	sysstick
CLOCK	On-chip	clock_control
PINMUX	On-chip	pinmux
UART	On-chip	serial port-polling

注：该端口目前不支持其他硬件功能。

默认配置可在 defconfig 文件中找到：[boards/xtensa/nxp_adsp_imx8m/nxp_adsp_imx8m_defconfig](#)。

4.2 连接和 I/Os

i.MX 8M Plus EVK 板使用以下 pinmux 控制器配置进行测试，如 [表 2](#) 所示。

表 2. 连接

电路板名称	SoC 名称	用途
UART4 RXD	UART4_TXD	UART 控制台
UART4 TXD	UART4_RXD	UART 控制台

4.3 系统时钟

HiFi 4 DSP 内核配置为以 800 MHz 时钟速度运行。

4.4 串行端口

i.MX 8M Plus SoC 有四个 UART。仅 UART_4 配置给了 DSP 控制台，其余 UART 没有被使用/测试。

5 在 HiFi 4 DSP 上构建和运行 Zephyr 示例

本节介绍在 HiFi 4 DSP 上构建和运行 Zephyr 示例的步骤：

- [章节 5.1](#)
- [章节 5.2](#)

5.1 hello_world 应用

[Zephyr's hello_world](#) 应用是一个简单的示例，支持用于多种 [Supported boards](#)，并在控制台中打印“Hello World”。

5.1.1 在 DSP 上加载 hello_world 应用

要在 DSP 上加载应用，请使用 Linux [remoteproc](#) 驱动程序。

在 Linux 中，可以使用 [i.MX remoteproc](#) 驱动程序和 DSP 特定驱动程序 ([imx_dsp_rproc](#))。

由于应用是在 DSP 上运行，因此要使用 `imx_dsp_rproc` 驱动程序。为此，请启用 Linux 内核中的 `CONFIG_IMX_DSP_REMOTEPROC`。

5.1.2 编译 hello_world application

在 Zephyr 中为 i.MX 8M Plus DSP（即 Zephyr 中的 `nxp_adsp_imx8m` 板）编译 `hello_world` 应用。

进入 `zephyrproject` 中的 `zephyr/` 文件夹并运行：

```
~/zephyrproject/zephyr$ west build -p always -b nxp_adsp_imx8m samples/
hello_world/
~/zephyrproject/zephyr$
~/zephyrproject/zephyr$ ls -la build/zephyr
total 4288
drwxr-xr-x 14 user nxp    4096 Oct 17 17:05 .
drwxr-xr-x  7 user nxp    4096 Oct 17 17:05 ..
drwxr-xr-x  5 user nxp    4096 Oct 17 17:05 arch
drwxr-xr-x  3 user nxp    4096 Oct 17 17:05 boards
drwxr-xr-x  5 user nxp    4096 Oct 17 17:05 cmake
-rw-r--r--  1 user nxp      64 Oct 17 17:05 .cmake.dotconfig.checksum
drwxr-xr-x  6 user nxp    4096 Oct 17 17:05 CMakeFiles
-rw-r--r--  1 user nxp  12355 Oct 17 17:05 cmake_install.cmake
-rw-r--r--  1 user nxp  39648 Oct 17 17:05 .config
...
-rw-r--r--  1 user nxp   2275 Oct 17 17:05 zephyr.dts
-rw-r--r--  1 user nxp    619 Oct 17 17:05 zephyr.dts.d
-rw-r--r--  1 user nxp 124460 Oct 17 17:05 zephyr.dts.pre
-rwxr-xr-x  1 user nxp  715896 Oct 17 17:05 zephyr.elf
-rw-r--r--  1 user nxp 408374 Oct 17 17:05 zephyr_final.map
-rw-r--r--  1 user nxp 408374 Oct 17 17:05 zephyr.map
-rwxr-xr-x  1 user nxp  717052 Oct 17 17:05 zephyr_pre0.elf
-rw-r--r--  1 user nxp  408886 Oct 17 17:05 zephyr_pre0.map
-rw-r--r--  1 user nxp   7273 Oct 17 17:05 zephyr.stat
```

`zephyr.elf` 文件将作为固件加载到 DSP 上。

5.1.3 在 DSP 上运行 hello_world 应用的步骤

以下是在 i.MX 8M Plus 的 HiFi 4 DSP 上运行 `hello_world` 应用的步骤。

5.1.3.1 启动 i.MX 8M Plus EVK 板

使用特定 DTS 启动 i.MX 8M Plus EVK 板。

使用 `imx8mp-evk-dsp.dtb`，插入 `imx_dsp_rproc.ko` 内核模块后，您就可以看到如下脚本：

```
root@imx8mpevk:~# ls -la /sys/class/remoteproc/
total 0
drwxr-xr-x  2 root root 0 Mar  3 09:49 .
drwxr-xr-x 90 root root 0 Mar  3 09:49 ..
lrwxrwxrwx  1 root root 0 Mar  3 09:54 remoteproc0 -> ../../devices/
platform/3b6e8000.dsp/remoteproc/remoteproc0
root@imx8mpevk:~# cat /sys/class/remoteproc/remoteproc0/firmware
imx/dsp/hifi4.bin
root@imx8mpevk:~#
```

由于 `remoteproc1` 用于 DSP，因此使用此模块。

5.1.3.2 检查电路板上的固件

检查电路板上的固件镜像：

```
root@imx8mpevk:~# ls -la /lib/firmware/imx/zephyr/
total 1256
drwxr-xr-x  2 root root   4096 Mar  3 11:03 .
drwxr-xr-x 12 root root   4096 Mar  9 2018 ..
-rwxr-xr-x  1 root root  41520 Mar  9 2018 imx8-hello_world-zephyr.elf
-rwxr-xr-x  1 root root  57100 Mar  9 2018 imx8m-hello_world-zephyr.elf
-rwxr-xr-x  1 root root 996276 Mar  3 10:38 imx8m-openamp_rsc_table-zephyr.elf
-rwxr-xr-x  1 root root  87876 Mar  9 2018 imx8m-philosophers-zephyr.elf
-rwxr-xr-x  1 root root  58124 Mar  9 2018 imx8m-synchronization-zephyr.elf
-rwxr-xr-x  1 root root  41520 Mar  9 2018 imx8x-hello_world-zephyr.elf
root@imx8mpevk:~#
```

在检测 `remoteproc` 驱动程序之前，固件必须存在于 `/lib/firmware` 中，但也可以使用绝对路径。

5.1.3.3 插入 `imx_dsp_rproc.ko` 内核模块

默认情况下，i.MX DSP `remoteproc` 协议等待远程处理器的 `READY` 回复。由于不是所有 Zephyr 示例应用（特别是不使用 `mailbox` 的简单应用）会发送 `READY` 回复，因此必须使用 `remoteproc` 模块，无需等待回复。这需要使用 `no_mailboxes` 内核模块参数来实现：

```
root@imx8mpevk:~# modinfo imx_dsp_rproc
filename:           /lib/modules/6.1.55-02981-g63bd8fa873a2/kernel/drivers/
remoteproc/imx_dsp_rproc.ko
author:             Shengjiu Wang <shengjiu.wang@nxp.com>
description:        i.MX HiFi Core Remote Processor Control Driver
license:            GPL v2
...
depends:
intree:             Y
name:               imx_dsp_rproc
parm:               no_mailboxes:There is no mailbox between cores, so ignore remote
proc reply after start, default is 0 (off). (int)
root@imx8mpevk:~#
```

默认情况下，`no_mailboxes` 参数是 `off`，即不忽略来自 `rproc` 的回复。

因此，首先检查 `imx_dsp_rproc` 参数。如果是 `off`，请删除模块，然后插入正确参数的模块。

```
root@imx8mpevk:~# grep -H ' ' /sys/module/imx_dsp_rproc/parameters/* /
*no_mailboxes param is off */
/sys/module/imx_dsp_rproc/parameters/no_mailboxes:0
root@imx8mpevk:~#
root@imx8mpevk:~# rmmod imx_dsp_rproc /* remove kernel module */
[ 797.922929] remoteproc remoteproc0: releasing imx-dsp-rproc
root@imx8mpevk:~#
root@imx8mpevk:~# modprobe imx_dsp_rproc no_mailboxes=1 /* insert kernel module
with the right parameter */
[ 819.930792] remoteproc remoteproc0: imx-dsp-rproc is available
root@imx8mpevk:~#
root@imx8mpevk:~# ls -la /sys/class/remoteproc/ /* now, we have remoteproc0, for
DSP */
```

```
total 0
drwxr-xr-x  2 root root 0 Mar  3 09:49 .
drwxr-xr-x 90 root root 0 Mar  3 09:49 ..
lrwxrwxrwx  1 root root 0 Mar  3 10:20 remoteproc0 -> ../../devices/
platform/3b6e8000.dsp/remoteproc/remoteproc0
root@imx8mpevk:~#
```

5.1.3.4 在 DSP 上加载并运行固件

要在 DSP 上加载固件并运行，请执行以下命令：

```
root@imx8mpevk:~# echo -n /lib/firmware/imx/zephyr/imx8m-hello-world-zephyr.elf
> /sys/class/remoteproc/remoteproc0/firmware
root@imx8mpevk:~# echo start > /sys/class/remoteproc/remoteproc0/state
[ 107.320099] remoteproc remoteproc0: powering up imx-dsp-rproc
[ 107.326031] remoteproc remoteproc0: Direct firmware load for /lib/firmware/
imx/zephyr/imx8m-hello-world-zephyr.elf failed with error -2
[ 107.336696] remoteproc remoteproc0: Falling back to sysfs fallback for: /lib/
firmware/imx/zephyr/imx8m-hello-world-zephyr.elf
[ 107.348365] remoteproc remoteproc0: Booting fw image /lib/firmware/imx/
zephyr/imx8m-hello-world-zephyr.elf, size 715896
[ 107.360096] remoteproc remoteproc0: no resource table found for this firmware
[ 107.367735] remoteproc remoteproc0: remote processor imx-dsp-rproc is now up
root@imx8mpevk:~#
```

5.1.3.5 停止固件

要停止固件，请执行以下命令：

```
root@imx8mpevk:~# echo stop > /sys/class/remoteproc/remoteproc0/state
[ 206.148281] remoteproc remoteproc0: stopped remote processor imx-dsp-rproc
root@imx8mpevk:~#
```

5.1.4 获取 hello_world 应用输出

为了获取 hello_world 应用输出，请遵循以下步骤：

1. 通过 UART 获取控制台。
2. 在第四串口上打开串口终端：

```
user@developerpc:~# minicom -D /dev/ttyUSB3
```

您将在终端上看到以下信息（也可在 [图 2](#) 中查询）：

```
Hello World! nxp_adsp_imx8m
*** Booting Zephyr OS build zephyr-v3.5.0-1510-gaa71ed4a1f55 ***
```

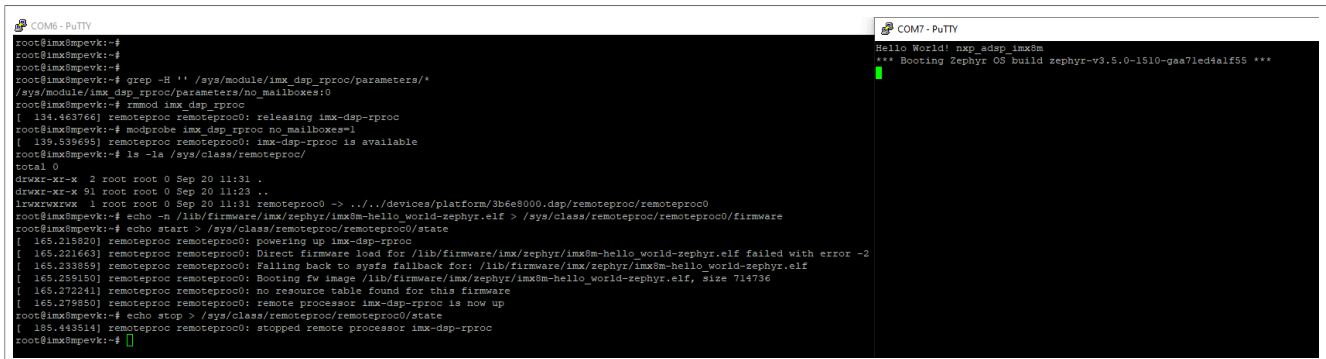


图 2. hello_world 应用输出

您可以使用上述步骤来构建和测试任何其他示例，例如 [synchronization](#) 或 [philosophers](#)。

您还可以运行更复杂的示例来演示 Linux 和 Zephyr 如何协同工作。下一节举例说明了 `openamp_rsc_table` 应用程序。

5.2 openamp_rsc_table 应用

[Zephyr's openamp_rsc_table](#) 应用演示了如何在 Zephyr 中基于资源表使用开放式非对称多处理（OpenAMP）。它旨在响应：

- [Linux rpmsg client sample](#)
- [Linux rpmsg tty driver](#)

此示例实现与在主处理器上嵌入 Linux 内核操作系统和在协处理器上嵌入 Zephyr 应用程序的平台兼容。

5.2.1 在 DSP 上加载 openamp_rsc_table 应用

如 [章节 5.1.1](#) 中所描述，要在 DSP 上加载 `openamp_rsc_table` 应用，请在 Linux 内核中启用 `CONFIG_IMX_DSP_REMOTEPROC` 后使用 `imx_dsp_rproc` 驱动程序。

5.2.2 在 Zephyr 中编译 openamp_rsc_table 应用

在 Zephyr 中为 i.MX 8M Plus DSP 编译 `openamp_rsc_table` 应用意味着为 `nxp_adsp_imx8m` 板编译应用。

进入 `zephyrproject` 中的 `zephyr/` 文件夹并运行：

```
~/zephyrproject/zephyr$ west build -p always -b nxp_adsp_imx8m samples/subsys/ipc/openamp_rsc_table
~/zephyrproject/zephyr$
~/zephyrproject/zephyr$ ls -la build/zephyr total 5284
drwxr-xr-x 14 nxa06898 nxp      4096 Sep 27 17:42 .
drwxr-xr-x  7 nxa06898 nxp      4096 Sep 27 17:42 ..
drwxr-xr-x  5 nxa06898 nxp      4096 Sep 27 17:42 arch
drwxr-xr-x  3 nxa06898 nxp      4096 Sep 27 17:42 boards
drwxr-xr-x  5 nxa06898 nxp      4096 Sep 27 17:42 cmake
-rw-r--r--  1 nxa06898 nxp         96 Sep 27 17:42 .cmake.dotconfig.checksum
drwxr-xr-x  6 nxa06898 nxp      4096 Sep 27 17:42 CMakeFiles
-rw-r--r--  1 nxa06898 nxp    13684 Sep 27 17:42 cmake_install.cmake
-rw-r--r--  1 nxa06898 nxp    41787 Sep 27 17:42 .config
drwxr-xr-x 16 nxa06898 nxp      4096 Sep 27 17:42 drivers
...
drwxr-xr-x  4 nxa06898 nxp      4096 Sep 27 17:42 soc
```



```
drwxr-xr-x 23 nxa06898 nxp 4096 Sep 27 17:42 subsys
-rw-r--r-- 1 nxa06898 nxp 2421 Sep 27 17:42 zephyr.dts
-rw-r--r-- 1 nxa06898 nxp 730 Sep 27 17:42 zephyr.dts.d
-rw-r--r-- 1 nxa06898 nxp 124812 Sep 27 17:42 zephyr.dts.pre
-rw-r--r-- 1 nxa06898 nxp 550701 Sep 27 17:42 zephyr_final.map
-rwxr-xr-x 1 nxa06898 nxp 998304 Sep 27 17:42 zephyr_openamp_rsc_table.elf
-rw-r--r-- 1 nxa06898 nxp 550701 Sep 27 17:42 zephyr_openamp_rsc_table.map
-rw-r--r-- 1 nxa06898 nxp 7463 Sep 27 17:42 zephyr_openamp_rsc_table.stat
-rwxr-xr-x 1 nxa06898 nxp 998476 Sep 27 17:42 zephyr_pre0.elf
-rw-r--r-- 1 nxa06898 nxp 551293 Sep 27 17:42 zephyr_pre0.map
...
```

The `zephyr_openamp_rsc_table.elf` file is used as the firmware to be loaded on the DSP.

5.2.3 在 Linux 中的 DSP 上运行 `openamp_rsc_table` 应用

以下小节介绍了如何在 Linux 中的 i.MX 8M Plus 板上的 HiFi 4 DSP 运行 `openamp_rsc_table` 应用。

`rpmsg_client_sample.ko` 和 `rpmsg_tty.ko` 模块用于与 DSP 上运行的 `openamp_rsc_table` 应用进行通信。这些是在主处理器（Cortex A 内核）上运行的示例模块。

要构建 `rpmsg_client_sample.ko` 和 `rpmsg_tty.ko` 模块，请分别在 Linux 内核中启用 `CONFIG_SAMPLE_RPMSG_CLIENT` and `CONFIG_RPMSG_TTY` 配置。

5.2.3.1 启动 i.MX 8M Plus EVK 板

使用特定的 DTS 启动 i.MX 8M Plus EVK 板。

使用 `imx8mp-evk-dsp.dtb`，插入 `imx_dsp_rproc.ko` 内核模块后得到：

```
root@imx8mpevk:~# insmod imx_dsp_rproc.ko
[ 115.172960] remoteproc remoteproc0: imx-dsp-rproc is available
root@imx8mpevk:~# ls -la /sys/class/remoteproc/
total 0
drwxr-xr-x 2 root root 0 Mar 3 09:49 .
drwxr-xr-x 90 root root 0 Mar 3 09:49 ..
lrwxrwxrwx 1 root root 0 Mar 3 20:09 remoteproc0 -> ../../devices/
platform/3b6e8000.dsp/remoteproc/remoteproc0
```

这里使用的是用于 DSP 的 `remoteproc0`。

5.2.3.2 检查板上固件

如要检查板上的固件镜像，请使用以下命令：

```
root@imx8mpevk:~# ls -la /lib/firmware/imx/zephyr/
total 148
drwxr-xr-x 2 root root 4096 Mar 9 2018 .
drwxr-xr-x 11 root root 4096 Mar 9 2018 ..
-rwxr-xr-x 1 root root 41524 Mar 9 2018 imx8-hello-world-zephyr.elf
-rwxr-xr-x 1 root root 57100 Mar 9 2018 imx8m-hello-world-zephyr.elf
-rwxr-xr-x 1 root root 41524 Mar 9 2018 imx8x-hello-world-zephyr.elf
-rwxr-xr-x 1 root root 998304 Mar 9 2018 imx8m-openamp_rsc_table-zephyr.elf
```

在探测 `remoteproc` 驱动程序之前，固件必须存在于 `/lib/firmware` 中；然而，它也可以用绝对路径给出。

5.2.3.3 插入 `imx_dsp_rproc.ko` 内核模块

如要插入 `imx_dsp_rproc.ko` 内核模块，请使用以下命令：

```
root@imx8mpevk:~# modprobe imx_dsp_rproc
[ 115.172960] remoteproc remoteproc0: imx-dsp-rproc is available
root@imx8mpevk:~# ls -la /sys/class/remoteproc/
total 0
drwxr-xr-x  2 root root 0 Mar  3 09:49 .
drwxr-xr-x 90 root root 0 Mar  3 09:49 ..
lrwxrwxrwx  1 root root 0 Mar  3 20:09 remoteproc0 -> ../../devices/
platform/3b6e8000.dsp/remoteproc/remoteproc0
```

5.2.3.4 插入 `rpmsg Linux` 客户端示例

如要插入 `rpmsg Linux` 客户端示例，请使用以下命令：

```
root@imx8mpevk:~# modprobe rpmsg_client_sample.ko /* rpmsg client sample
driver used to communicate with remote processor over the rpmsg bus */
root@imx8mpevk:~# modprobe rpmsg_tty.ko /* export rpmsg endpoints
as tty devices, usually found as /dev/ttyRPMSGx */
```

5.2.3.5 在 DSP 上加载并运行固件

5.2.3.5.1 `rpmsg` 客户端示例

从 Linux 向 Zephyr 发送 100 条带有 "hello world" 的消息。

Linux 控制台：

```
root@imx8mpevk:~# echo -n zephyr_openamp_rsc_table.elf > /sys/class/remoteproc/
remoteproc0/firmware
root@imx8mpevk:~# echo start > /sys/class/remoteproc/remoteproc0/state
[ 200.630824] remoteproc remoteproc0: powering up imx-dsp-rproc
[ 200.637393] remoteproc remoteproc0: Booting fw image
zephyr_openamp_rsc_table.elf, size 999412
[ 200.649895] rproc-virtio rproc-virtio.2.auto: assigned reserved memory node
vdev0buffer@94300000
[ 200.662289] virtio_rpmsg_bus virtio0: rpmsg host is online
[ 200.667889] rproc-virtio rproc-virtio.2.auto: registered virtio0 (type 7)
[ 200.674715] remoteproc remoteproc0: remote processor imx-dsp-rproc is now up
[ 200.681908] virtio_rpmsg_bus virtio0: creating channel rpmsg-client-sample
addr 0x400
[ 200.689959] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: new
channel: 0x400 -> 0x400!
[ 200.700409] virtio_rpmsg_bus virtio0: creating channel rpmsg-tty addr 0x401
[ 200.707894] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: incoming
msg 1 (src: 0x400)
[ 200.717703] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: incoming
msg 2 (src: 0x400)
[ 200.726580] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: incoming
msg 3 (src: 0x400)
[ 200.735433] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: incoming
msg 4 (src: 0x400)
[ 200.744289] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: incoming
msg 5 (src: 0x400)
```

```
[ 200.753158] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: incoming
msg 6 (src: 0x400)
[ 200.761988] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: incoming
msg 7 (src: 0x400)
[ 200.770827] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: incoming
msg 8 (src: 0x400)
[ 200.779680] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: incoming
msg 9 (src: 0x400)
[ 200.788511] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: incoming
msg 10 (src: 0x400)
...
[ 201.529273] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: incoming
msg 93 (src: 0x400)
[ 201.538195] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: incoming
msg 94 (src: 0x400)
[ 201.547120] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: incoming
msg 95 (src: 0x400)
[ 201.556048] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: incoming
msg 96 (src: 0x400)
[ 201.564975] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: incoming
msg 97 (src: 0x400)
[ 201.573901] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: incoming
msg 98 (src: 0x400)
[ 201.582816] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: incoming
msg 99 (src: 0x400)
[ 201.591742] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: incoming
msg 100 (src: 0x400)
[ 201.600716] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: goodbye!
[ 201.607877] virtio_rpmsg_bus virtio0: destroying channel rpmsg-client-sample
addr 0x400
[ 201.615953] rpmsg_client_sample virtio0.rpmsg-client-sample.-1.1024: rpmsg
sample client driver is removed
```

Zephyr 控制台:

```
*** Booting Zephyr OS build zephyr-v3.4.0-4490-gd885048637d6 ***
Starting application threads!

OpenAMP[remote] linux responder demo started

OpenAMP[remote] Linux sample client responder started

[00:00:00.015,000] <dbg> openamp_rsc_table: platform_ipm_callback:
platform_ipm_callback: msg received from mb 0

[00:00:00.020,000] <dbg> openamp_rsc_table: mailbox_notify: mailbox_notify: msg
received

[00:00:00.024,000] <dbg> openamp_rsc_table: mailbox_notify: mailbox_notify: msg
received

[00:00:00.053,000] <dbg> openamp_rsc_table: platform_ipm_callback:
platform_ipm_callback: msg received from mb 0

[00:00:00.053,000] <dbg> openamp_rsc_table: mailbox_notify: mailbox_notify: msg
received

[00:00:00.070,000] <dbg> openamp_rsc_table: platform_ipm_callback:
platform_ipm_callback: msg received from mb 0
```

```
[00:00:00.070,000] <dbg> openamp_rsc_table: mailbox_notify: mailbox_notify: msg
received

[00:00:00.079,000] <dbg> openamp_rsc_table: platform_ipm_callback:
platform_ipm_callback: msg received from mb 0

[00:00:00.079,000] <dbg> openamp_rsc_table: mailbox_notify: mailbox_notify: msg
received

[00:00:00.088,000] <dbg> openamp_rsc_table: platform_ipm_callback:
platform_ipm_callback: msg received from mb 0

[00:00:00.088,000] <dbg> openamp_rsc_table: mailbox_notify: mailbox_notify: msg
received

[00:00:00.097,000] <dbg> openamp_rsc_table: platform_ipm_callback:
platform_ipm_callback: msg received from mb 0

...

[00:00:00.935,000] <dbg> openamp_rsc_table: platform_ipm_callback:
platform_ipm_callback: msg received from mb 0

[00:00:00.935,000] <dbg> openamp_rsc_table: mailbox_notify: mailbox_notify: msg
received

[00:00:00.944,000] <dbg> openamp_rsc_table: platform_ipm_callback:
platform_ipm_callback: msg received from mb 0

[00:00:00.944,000] <dbg> openamp_rsc_table: mailbox_notify: mailbox_notify: msg
received

[00:00:00.944,000] <dbg> openamp_rsc_table: mailbox_notify: mailbox_notify: msg
received
```

5.2.3.5.2 rpmsg TTY 演示

在 Linux 控制台上，向 Zephyr 发送信息，其使用 “TTY <add>” 前缀进行回复。<add> 为 Zephyr rpmsg-tty 的地址。

Linux 控制台：

```
root@imx8mpevk:~# cat /dev/ttyRPMSG0 &
[1] 1540
root@imx8mpevk:~# echo "Hello Zephyr" >/dev/ttyRPMSG0
TTY 0x0401: Hello Zephyr
root@imx8mpevk:~#
```

Zephyr 控制台：

```
*** Booting Zephyr OS build zephyr-v3.4.0-4490-gd885048637d6 ***
Starting application threads!

OpenAMP[remote] linux responder demo started

OpenAMP[remote] Linux tty responder started

[00:06:02.049,000] <dbg> openamp_rsc_table: platform_ipm_callback:
platform_ipm_callback: msg received from mb 0
```

```
[00:06:02.049,000] <dbg> openamp_rsc_table: mailbox_notify: mailbox_notify: msg received
```

5.2.3.6 停止固件

要停止固件，请使用以下命令：

```
root@imx8mpvdk:~# echo stop > /sys/class/remoteproc/remoteproc0/state
[ 495.366531] remoteproc remoteproc0: stopped remote processor imx-dsp-rproc
```

5.2.4 获取 openamp_rsc_table 应用输出

要获取 openamp_rsc_table 应用输出，请执行以下步骤：

1. 通过UART获取控制台。
2. 在第四个串行端口上打开串行终端：

```
user@developerpc:~# minicom -D /dev/ttyUSB3
```

您在终端中看到以下消息（也显示在 图 3）：

```
*** Booting Zephyr OS build zephyr-v3.4.0-4490-gd885048637d6 ***
Starting application threads!

OpenAMP[remote] linux responder demo started

OpenAMP[remote] Linux sample client responder started

OpenAMP[remote] Linux tty responder started
[00:00:00.015,000] <dbg> openamp_rsc_table: platform_ipm_callback:
platform_ipm_callback: msg received from mb 0
```

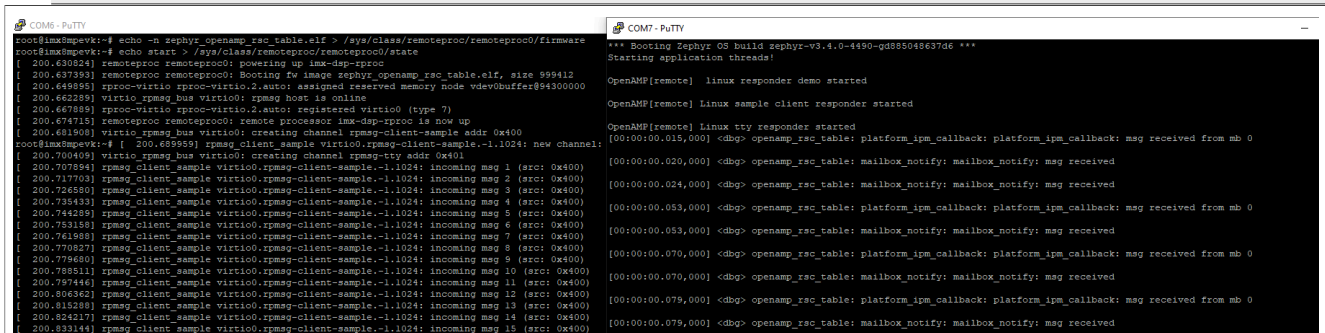


图 3. openamp_rsc_table 应用输出

6 缩略语

Table 3 列出了本文档中使用的缩略语。

Table 3. 缩略语

缩略语	全称
DSP	Digital signal processor

Table 3. 缩略语...continued

缩略语	全称
DTS	Device tree source
IPC	Inter-process communication
MCU	Microcontroller unit
MPU	Microprocessor unit
OpenAMP	Open Asymmetric Multi-Processing
OS	Operating system
rproc	Remote processor
rsc_table	Resource table
RTOS	Real-time operating system
UART	Universal Asynchronous Receiver/Transmitter

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8 修订记录

表 4 汇总了自初始版以来对本文档所做的更改。

表 4. 修订记录

版本号	日期	说明
2	2023 年 11 月 28 日	<ul style="list-style-type: none"> 更新以下章节： <ul style="list-style-type: none"> - 章节 5.1.2 - 章节 5.1.3.1 - 章节 5.1.3.2

表 4. 修订记录...续上页

版本号	日期	说明
		<ul style="list-style-type: none">- 章节 5.1.3.3- 章节 5.1.3.4- 章节 5.1.3.5- 章节 5.1.4• 增加新章节: 章节 5.2
1	2023 年 6 月 1 日	初次发布

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